

Linear-Time Computation of a Linear Kernel for Dominating Set on Planar Graphs

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Worker 2011

Planar Dominating Set

Input A planar graph G and an integer k .

Question Is there a dominating set of size k for G ?

- $\gamma(G)$ = size of minimum dominating set of G

Known Results:

- GAREY & JOHNSON, 1979: NP-hardness
- BAKER, J. ACM 1994: PTAS
- subexponential algorithms:
 - ALBER, BODLAENDER, FERNAU, KLOKS & NIEDERMEIER, ALGORITHMICA 2002

Focusing on Kernel Size:

Alber, Fellows & Niedermeier, J. ACM 2004:

335γ -vertex kernel in $O(n^3)$ time

CHEN, FERNAU, KANJ & XIA, SIAM J. COMPUT. 2007:

67γ -vertex kernel in $O(n^3)$ time

Focusing on Larger Graph Classes:

FOMIN & THILIKOS, ICALP 2004:

$O(\gamma + g)$ -vertex kernel in $O(gn^3)$ time on graphs of genus g

PHILIP, RAMAN & SIKDAR, ESA 2009:

$O(\gamma^{2(d+1)^2})$ -vertex kernel in $O(2^d dn^2)$ time on d -degenerated graphs

FOMIN, LOKSHTANOV, SAURABH & THILIKOS, SODA 2010:

$O(\gamma)$ -vertex kernel in polynomial time on apex-minor free graphs

VAN BEVERN, HARTUNG, KAMMER, NIEDERMEIER & WELLER, IPEC 2011:
 $O(\gamma)$ -vertex kernel in $O(n)$ time

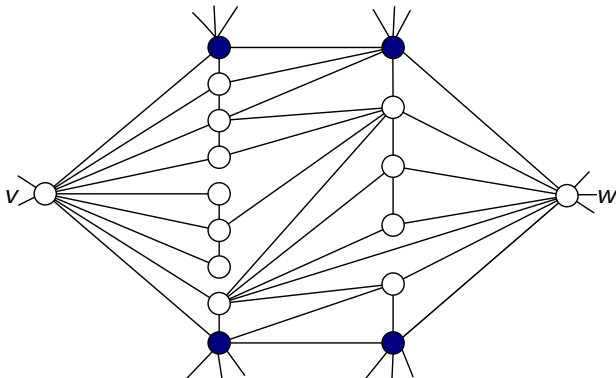
Motivation:

- kernel size \Leftrightarrow running time of kernelization
 - Which kernel size can be achieved in linear time?
 - combine **size-optimized** with **time-optimized** kernelization algorithm
 - with CHEN ET AL., 2007: 67γ -vertex kernel in $O(\gamma^3 + n)$ time

Main Features:

- rework and more refined analysis of the interaction of the reduction rules of ALBER ET AL., 2004
- non-exhaustive application of rules \rightarrow “knowing when to stop”

Main Observation: A graph is decomposable into $O(\gamma)$ regions.

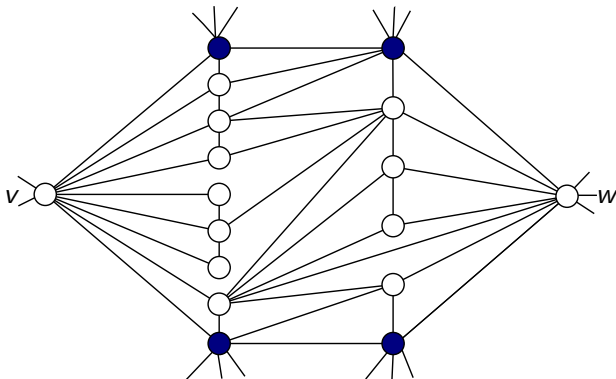


Definition

A region between two vertices v and w is a closed subset of the plane such that

- ① all vertices are contained in $N(v) \cup N(w)$, and
- ② the boundary is formed by two simple paths of length at most three.

Main Observation: A graph is decomposable into $O(\gamma)$ regions.

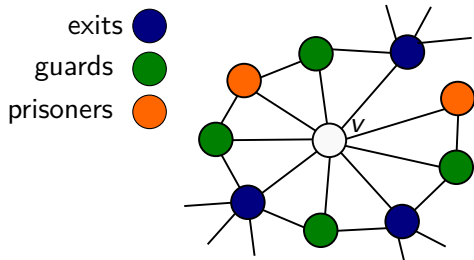


Problem kernel is obtained by two reduction rules:

- 1 **Private Neighborhood:** Reduces number of vertices outside of regions to $O(\gamma)$
- 2 **Joint Neighborhood:** Shrink each region to $O(1)$ vertices

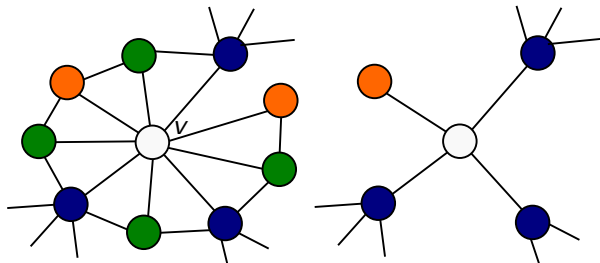
Alber et al.: Private Neighborhood Rule

- partition the neighborhood of a vertex v into three sets



Alber et al.: Private Neighborhood Rule

- partition the neighborhood of a vertex v into three sets

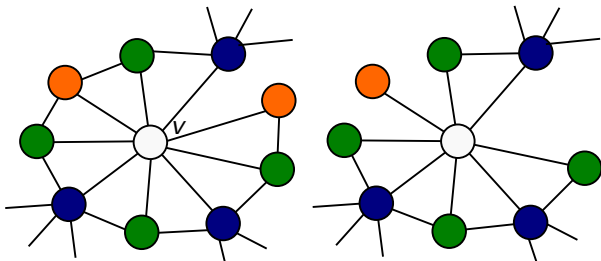


Private Neighborhood Rule

Delete guards and prisoners and add a degree-one neighbor.

Alber et al.: Private Neighborhood Rule

- partition the neighborhood of a vertex v into three sets



Private Neighborhood Rule

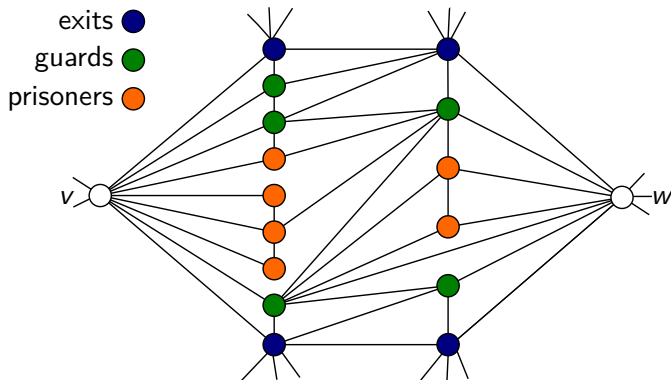
Delete guards and prisoners and add a degree-one neighbor.

Modified Private Neighborhood Rule

Delete prisoners and add a degree-one neighbor.

- avoids **cascading effects** → exhaustive application in $O(n)$ time

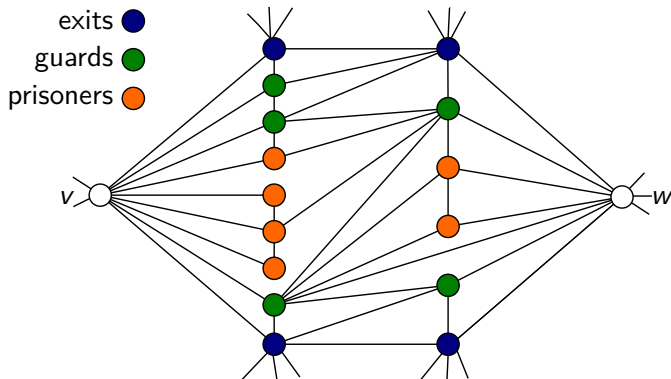
Joint Neighborhood Rule: **Finds and Shrinks Regions**



Shrink every **potential region**:

- Alber et al.: For all vertices v, w delete vertices from $N(v) \cup N(w) \rightarrow \Omega(n^2)$. Rule applies $O(n)$ times $\rightarrow O(n^3)$ time

Joint Neighborhood Rule: **Finds and Shrinks Regions**

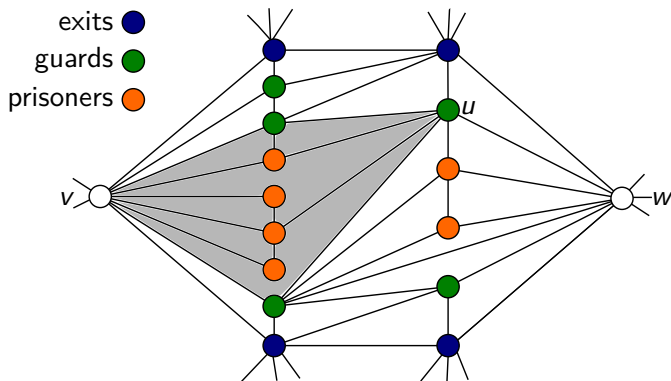


Shrink every **potential region**:

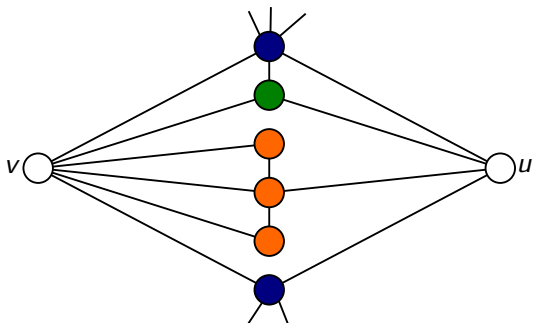
- **Modified Joint Neighborhood Rule:**
 - DFS: starting in v , list all vertices up to a depth of three
 - follow only constant degree vertices

Our Main Observation:

- the neighbors of inner vertices lie in the region \rightarrow adjacent to v or w
- inner vertices with large degree form **restricted regions**



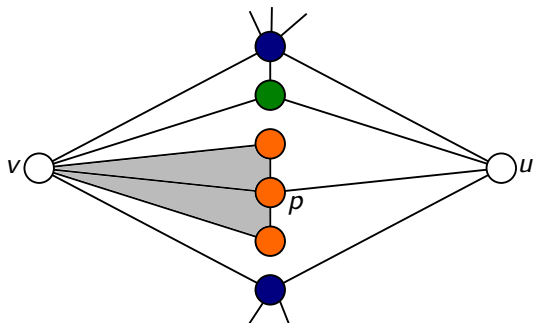
Restricted Regions I



Observations:

- all inner vertices have to be adjacent to v
- boundary paths have length at most two

Restricted Regions I



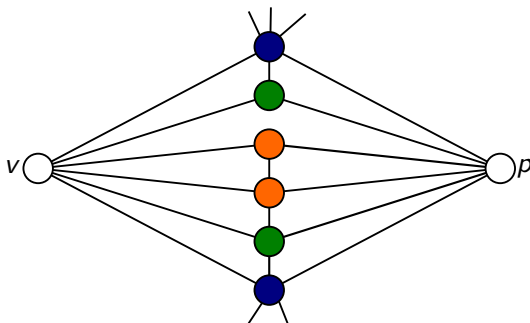
Observations:

- all inner vertices have to be adjacent to v
- boundary paths have length at most two
- a common neighbor $p \in N(u) \cap N(v)$ can still have **unbounded degree**
 - \rightarrow consider the restricted region between v and p

Restricted Region II

Observations:

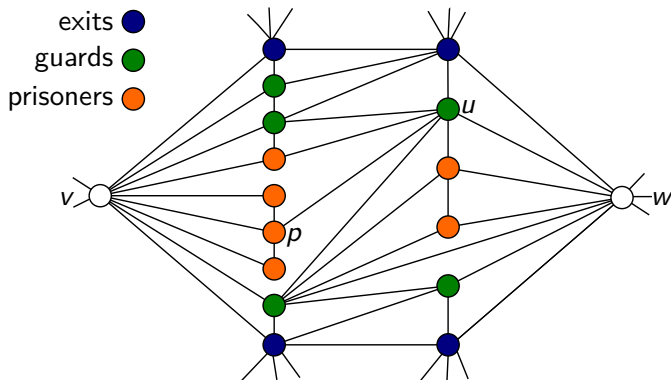
- all inner vertices have to be **adjacent to v and p**
 - planarity: **inner vertices have constant degree!**



- $v - p$ region can be explored in time bounded by the number of inner vertices → **Modified Joint Neighborhood Rule**

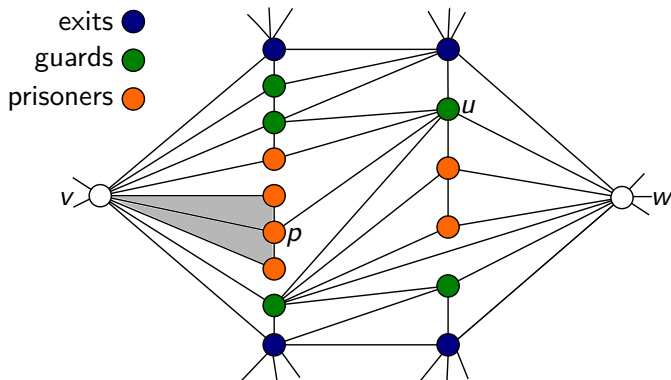
Kernelization Algorithm

- 1 Modified Private Neighborhood Rule: Shrinks vertices outside of regions



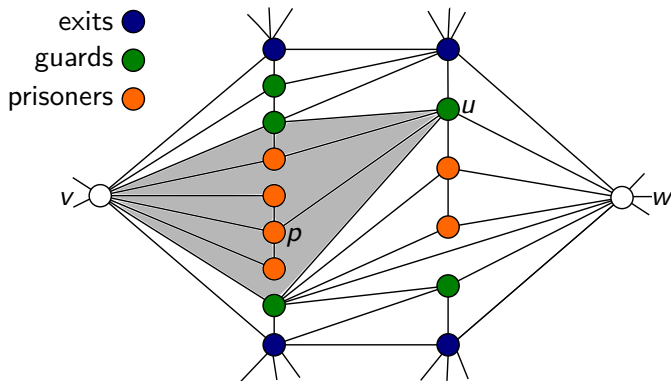
Kernelization Algorithm

- 1 Modified Private Neighborhood Rule: Shrinks vertices outside of regions
- 2 Modified Joint Neighborhood Rule: Shrinks $v - p$ region $\rightarrow \deg(p)$ constant



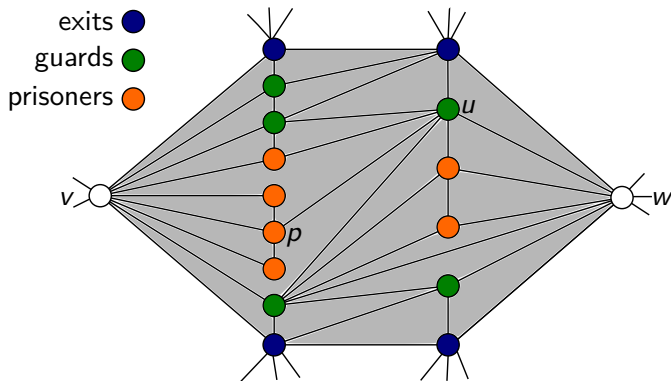
Kernelization Algorithm

- 1 Modified Private Neighborhood Rule: Shrinks vertices outside of regions
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- 3 Modified Joint Neighborhood Rule: Shrinks $v - u$ region $\rightarrow \deg(u)$ constant



Kernelization Algorithm

- 1 Modified Private Neighborhood Rule: Shrinks vertices outside of regions
- 2 Modified Joint Neighborhood Rule: Shrinks $v - p$ region $\rightarrow \deg(p)$ constant
- 3 Modified Joint Neighborhood Rule: Shrinks $v - u$ region $\rightarrow \deg(u)$ constant
- 4 Modified Joint Neighborhood Rule: Shrinks $v - w$ region to constant size



- kernel size and kernel time race
 - combining them yields fast and effective preprocessing for hard problems
- approaches to get time-optimized kernels:
 - 1 Speed-up known kernels (our work)
 - 2 Develop new time-optimized kernels
 - HAGERUP, IPEC 2011, LINEAR-TIME KERNELIZATION FOR PLANAR DOMINATING SET

- implementation of our approach
 - 335 γ kernel: ALBER, BETZLER & NIEDERMEIER, ANN. OPER. RES., 2006
- Exhaustive application of reduction rules of Alber et al. (or even Chen et al.) in linear time?
- Can our approach be extended to other problems?
 - CONNECTED VERTEX COVER
 - GUO & NIEDERMEIER, ICALP 2007
- Lower Bounds: Does every FPT-problem admit a kernel in $O(n)$ time?
 - near-linear time: best kernel in $O(p(k) + n)$ or $O(p(k) \cdot n)$ time?